S21501 Tuning GPU Server for Deep Learning Performance

Dell EMC HPC & AI Innovation Lab

Frank Han : frank.han@dell.com Rengan Xu : rengan.xu@dell.com



Agenda

- The goal of this session
- About us/HPC innovation lab
- MLPerf
- Our testing bed
- Single nodes training finding
- Multiple nodes training
- Inference

Goal of this session

- Show some possible tuning knobs
- Share results from our tuning
- More RFPs are using MLPerf
- Next version submission

HPC and DL Engineering - what we do

- Design and build systems for HPC and Deep Learning workloads.
- **Systems** include compute, storage, network, software, services, support.
- Integration with factory, software, services.
- Power and performance analysis, tuning, best practices, trade-offs.
- Focus on **application** performance.
- Vertical solutions.
- Research and **proof of concept** studies.
- Publish white papers, blogs, conference papers (<u>www.hpcatdell.com</u>)
- Access to the systems in the lab



World-class infrastructure in the Innovation Lab

13K ft.² lab, 1,300+ servers, ~10PB storage dedicated to HPC in collaboration with the community

Zenith

- TOP500-class system based on Intel Scalable Systems Framework (OPA, KNL, Xeon, OpenHPC)
- 424 nodes dual Intel Xeon Gold processors, Omni-Path fabric.
- +160 Intel Xeon Phi (KNL) servers.
- Over 1 PF combined performance!
- #265 on Top500 June 2018, 1.86 PF theoretical peak
- Lustre, Isilon H600, Isilon F800 and NSS storage
- Liquid cooled and air cooled

Rattler

- Research/development system with Mellanox, NVIDIA and Bright Computing
- 88 nodes with EDR InfiniBand and Intel Xeon Gold processors
- 32x PowerEdge C4140 nodes with 4x NVIDIA GPUs

Other systems

• 32 node AMD cluster, storage solutions, etc.







MLPerf training Introduction

Benchmark	Dataset	Quality Target	Reference Implementation Model
Image classification	ImageNet (224x224)	75.9% Top-1 Accuracy	Resnet-50 v1.5
Object detection (light weight)	COCO 2017	23% mAP	SSD-ResNet34
Object detection (heavy weight)	COCO 2017	0.377 Box min AP, 0.339 Mask min AP	Mask R-CNN
Translation (recurrent)	WMT English-German	24.0 BLEU	GNMT
Translation (non-recurrent)	WMT English-German	25.0 BLEU	Transformer
Recommendation	Undergoing modification		
Reinforcement learning	N/A	Pre-trained checkpoint	Mini Go

- A broad ML benchmark suite for measuring performance of ML frameworks, ML hardware accelerators, and ML cloud platforms.
- Cover different DL domains
- Proper metrics (training time, accuracy)
- Real datasets

Who did what in MLPerf training v0.6

DELL

NVIDIA/Others

MLPerf Community

- Dell server optimization
 - CPU binding
 - BIOS HT
 - Batch Size/Learning rate/Warm-up steps/etc.
 - NCCL P2P & Tree/Ring vs DGX-1 optimized
- Select framework
- Code optimization by each team
 - NCCL 2.3 -> 2.4.7
 - DALI
 - Active function
 - Multiple GPU(Horovod)
- DGX optimization
 - Batch Size
 - etc.
- Define the Sub-benchmarks
 - Accuracy
 - Models
 - Datasets
- Github sample codes 1xP100

MLPerf v0.5 and v0.6 difference – MLPerf community

- Raises quality targets:
 - Image classification (ResNet) to 75.9% (v0.5 was 74.9%)
 - light-weight object detection (SSD) to 23% mAP (v0.5 was 21.2%)
 - recurrent translation (GNMT) to 24 Sacre BLEU (v0.5 was 21.8)
- Allows use of the LARS optimizer for ResNet, enabling additional scaling
- Experimentally allows a slightly larger set of hyperparameters to be tuned
 - Enabling faster performance and some additional scaling
- Changes timing to start the first time the application accesses the training dataset, thereby excluding startup overhead
 - This change was made because the large scale systems measured are typically used with much larger datasets than those in MLPerf, and hence normally amortize the startup overhead over much greater training time
- Improves the MiniGo benchmark in two ways
 - First, it now uses a standard C++ engine for the non-ML compute, which is substantially faster than the prior Python engine.
 - Second, it now assesses quality by comparing to a known-good checkpoint, which is more reliable than the previous very small set of game data
- Suspends the Recommendation benchmark while a larger dataset and model are being created

Resnet-50 v0.6 improvement - NVIDIA

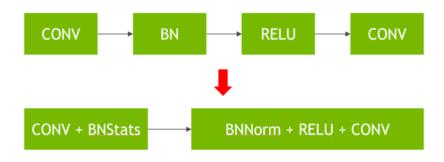
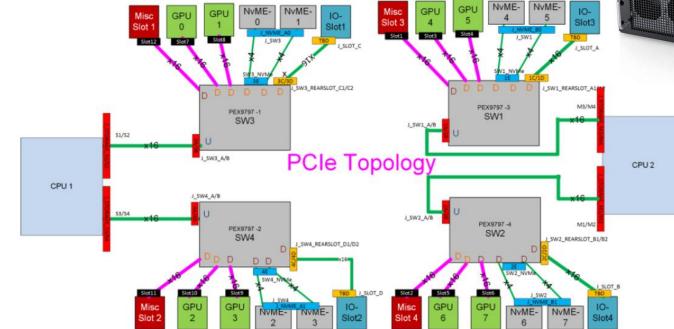


Figure 1. New fused convolution + batchnorm kernels make better use of Tensor Cores and halve the number of discrete kernels that need to run

- Image Classification / ResNet-50 (1.24x improvement). Implemented new fused convolution + batchnorm kernels through cuDNN 7.6.
 - This optimization drastically reduces the cost of batch normalization (a bandwidth-limited operation and does not benefit from Tensor Cores) by performing the normalization in adjacent convolution layers, as outlined in figure 1.
- A variety of DALI-related improvements accelerated the data input pipeline, enabling it to keep up with high-speed neural network processing.
 - These include using NVJPEG and ROI JPEG decode to limit the JPEG decode work to the region of the raw image actually used.
 We also used Horovod for data parallel execution, allowing us to hide the exchange of gradients between GPUs behind other back-propagation work happening on the GPU.



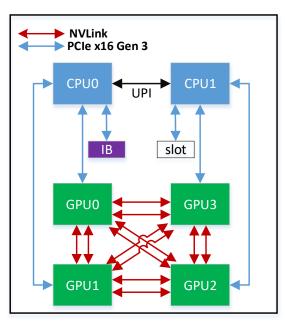
Dell EMC DSS8440



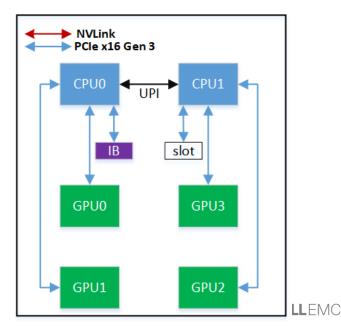


C4140M – NVLINK System

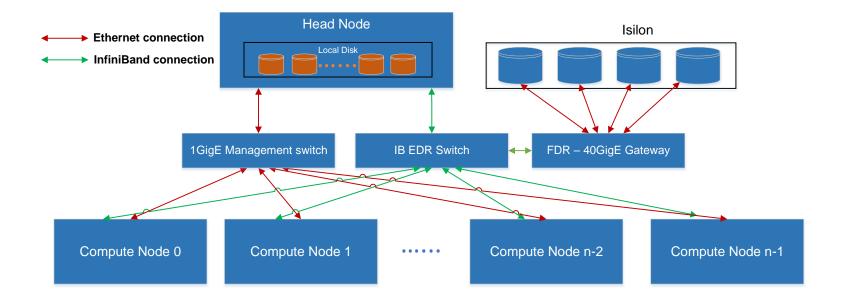
- All accelerators are put at the front
- The Only Dell system has NVLINK
- Smaller failure zone
- Dual redundant PSU







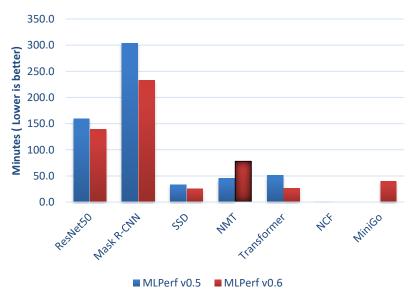
Our cluster



Single nodes

MLPerf results – Original NVIDIA docker run on DSS8440

MLPerf v0.5 vs v0.6



Network	Server - DSS8440			
	MLPerf v0.5	MLPerf v0.6		
ResNet50-v1.5	159.6	139.0		
Mask R-CNN	304.0	232.6		
SSD	33.2	25.7		
NMT	45.3	<mark>78.0</mark>		
Transformer	51.0	26.7		
NCF	1.0	N/A		
MiniGo	N/A	34.0		

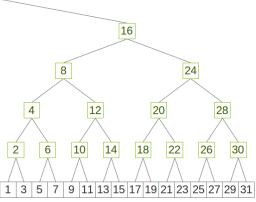
- Time taken to converge GNMT from v0.5 to v0.6 is significantly high.
- Analysis in the next slides

GNMT Profiling results

[root@dss01 rnn_t ======== Profilin	ranslator q result:]# nvprof ·	∙i gnmt.nv	vp20190724	182831.499		
	Time(%)	Time	Calls	Avg			Name
GPU activities:	59.65%	534.420s	970	550.95ms	96.596ms	848.15ms	ncclAllReduceRingLLKernel_sum_f16(ncclColl)
	10.35%	92.7072s	674052	137.54us	85.567us	393.18us	<u>volta_fpl6_s884gemm_fpl6_128x64_ldg8_f2f_nn</u>
	6.35%	56.8967s	169372	335.93us	125.22us	33.244ms	volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn
	5.79%	51.8429s	166814	310.78us	190.97us	4.8022ms	volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nn
	4.50%	40.2976s	12484	3.2279ms	165.53us	9.2248ms	volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nt
	3.06%	27.4563s					volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nt
	1.75%	15.6660s	3225	4.8577ms	44.831us	31.040ms	volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_tn
		10.7461s	335902	31.991us	2.6880us	75.679us	void LSTM_elementWise_fp <half,half, cudnnrn<="" float,="" td=""></half,half,>
e_t=2>(int, int,	int, int,	half cor	1st *,h	alf const	*,half	const *, _	_half const *, cudnn::reduced_divisor,half*,half*,
<pre>,half const *,</pre>	half*,	bool, int,	cudnnRNN	ClipMode_t	, cudnnNan	Propagatio	m_t, float, float)
	1 11%	0 06056c	33/1286	20 706119	17 18/lus	72 31Que	void LSTM elementWise bold half balf floats(int i

• Analysis using "nvprof" profiling tool show most of the time (524.42s) is spent on ncclAllReduceRing communication

[root@dss01 rnn tr	ranslator]# head -7	*.nvprof					https://devblogs.nvidia.com/massively-scale-deep-learning-training-nccl-2-4/
==> Ring_p2p1.nvpr	rof <==							
======= Profiling								0
	Time(%)	Time	Calls	Avg	Min	Max		
GPU activities:		140.7175	970			1.11446s	<pre>ncclAllReduceRingLLKernel_sum_f16(ncclColl)</pre>	
		92.9812s	674052			393.31us	volta_fp16_s884gemm_fp16_128x64_ldg8_f2f_nn	16
		57.1649s		337.51us			volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn	10
		51.9953s		311.70us			volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nn	
	8.01%	40.2951s	12484	3.2277ms	170.65us	9.1541ms	volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nt	
	cot							8 24
==> Ring_p2p3.nvpr ======== Profiling								0
	J result: Time(%)	Time	Calls	Avg	Min	Max	Name	
GPU activities:		519.359s		535.42ms		787.84ms	ncclAllReduceRingLLKernel sum f16(ncclColl)	
OPO activities.		92.42775	674052		85.727us			4 12 20 28
		56.8969s	169372		124.09us		volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn	
		52.1251s	166814					$\land \qquad \land \qquad \land \qquad \land \qquad \land$
	4.58%	40.30895						
				3	1001100	5 1 1 2 1 0 1	Votta_Ipio_soo igenim_Ipio_cookico_tage_ici_ii	
==> Ring_p2p5.nvpr	of <==							2 6 10 14 18 22 26 30
======== Profiling								$\overline{\land} \land \land \land \land \land \land \land \land \land \land$
	Time(%)	Time	Calls	Avg	Min	Max	Name	
GPU activities:		588.464s	970			1.04102s		
		93.0078s	674052		85.503us			1 3 5 7 9 11 13 15 17 19 21 23 25 27 29 31
		57.1875s						
	5.50%	52.4149s	166814			4.8320ms		
	4.26%	40.6027s		3.2524ms				Figure 4. Disperators using a network of two pattern
								Figure 1. Binary tree using a power-of-two pattern
==> Tree_p2p1.nvpr								NCCL_P2P_LEVEL
====== Profiling	g result:							
	Time(%)	Time	Calls	Avg	Min	Max		(since 2.3.4)
GPU activities:	40.49%	247.853s	970	255.52ms		1.06158s	ncclAllReduceTreeLLKernel_sum_f16(ncclColl)	laura
		93.8892s	674052					The NCCL_P2P_LEVEL variable allows the user to finely control when to use the peer to peer (P2P)
		57.4789s	169372			33.342ms	volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn	transport between GPUs. The level defines the maximum distance between GPUs where NCCL will
		51.9241s		311.27us	199.20us		volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nn	use the P2P transport.
	6.63%	40 <u>5821s</u>	12484	3.2507ms	172.86us	9.3337ms	volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nt	use the rzr transport.
								77-1
==> Tree_p2p5_2.nv								Values accepted
======= Profiling								0 : Never use P2P. (always disabled)
	Time(%)	Time	Calls	Avg	Min	Max		0. Nevel use P2P. (aiways uisableu)
GPU activities:		363.391s		374.63ms		988.59ms	ncclAllReduceTreeLLKernel_sum_f16(ncclColl)	1 : Use P2P when GPUs are on the same PCI switch.
		93.24435	674052					1: Use P2P when Gros are on the same rci switch.
		57.3899s	169372				volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn	
		52.5207s	166814		199.61us		volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nn	2 : Use P2P when GPUs are connected through PCI switches (potentially multiple hops).
	5.58%	40.5722s	12484	3.2499ms	173.34us	9.3915ms	volta_fp16_s884gemm_fp16_256x128_ldg8_f2f_nt	
T	6 .							3 : Use P2P when GPUs are on the same PCI root complex, potentially going through the CPU.
==> Tree_p2p5.nvpr								
======= Profiling			Calls	Aug	Min	Max		4 : (Since 2.4.7) Use P2P even across PCI root complexes, as long as the GPUs are within the same
	Time(%)	Time		Avg	Min 02 107mg	Max		NUMA node. (Before 2.4.7) Use P2P even across PCI root complexes, regardless of whether the
GPU activities:		406.117s		418.68ms		819.33ms	<pre>ncclAllReduceTreeLLKernel_sum_f16(ncclColl) walta_fal6_s884aamm_fal6_l28x64_lda8_f2f_nn</pre>	GPUs are within the same NUMA node (always enabled).
		93.2616s 57.2983s	674052 169372			401.72us 33.220ms	volta_fp16_s884gemm_fp16_128x64_ldg8_f2f_nn volta_fp16_s884gemm_fp16_128x128_ldg8_f2f_nn	
		57.2983s 52.3837s			125.31us 198.78us		volta_tp16_s884gemm_tp16_128x128_ldg8_t2t_nn volta fp16 s884gemm fp16 256x128 ldg8 f2f nn	5 : Use P2P even across the SMP interconnect between NUMA nodes (e.g., QPI/UPI). (always
		52.3837s 40.5771s	166814	314.02Us 3.2503ms	198.78us 173.31us		volta_tp16_s884gemm_tp16_256x128_ldg8_t2t_nn volta fp16 s884gemm fp16 256x128 ldg8 f2f nt	enabled)
[root@dss01 rnn tr			12404	3.2505005	1/3.5105	9.1597115	Volta_tp16_\$884gemm_tp16_250x126_tug6_t21_ft	
	ans caco]#						The default value is 3.

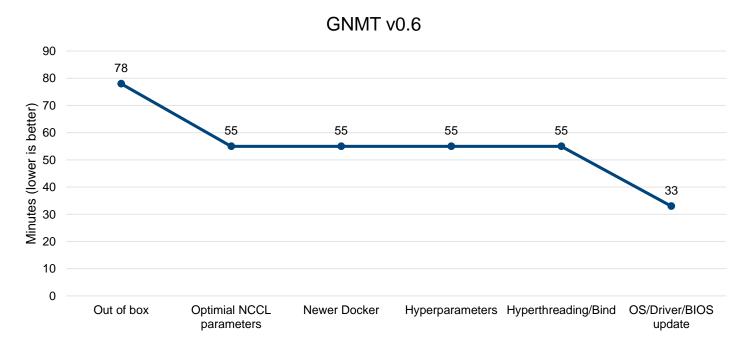


P_LEVEL

epted

ttps://docs.pvidia.com/deeplearning/sdk/pccl-developer-guide/docs/epv.html

GNMT on DSS8440



- NVIDIA docker is optimal based on DGX-1
- PCIe system need fine tune to make sure software matches with hardware topology
- We are able to reduce the training time from 77 min to 33 min on DSS8440
- Reduces overall time to 70%

Tuning Knobs - HW

- CPU cores frequency
 - 6230 2.1 GHz/20cores
 - 6248 2.5 GHz/20cores
 - 6252 2.1 GHz/24cores
- Memory 2666 vs 2933
- PCIe vs NVLink
 - Except GNMT and Transformer ~30%
 - ~10% both single and multiple nodes
 - TDP 250 vs 300 W & Higher frequency
- Storage
 - Local SSD
 - U.2 NVMe
 - Isilon
 - Lustre

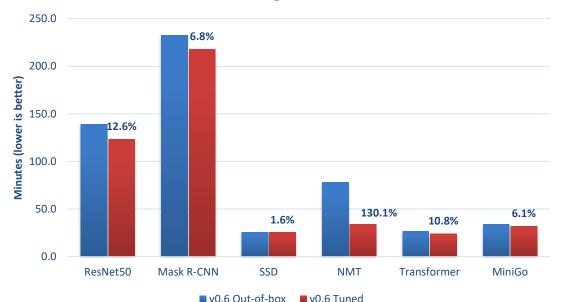
- BIOS
 - Custom profile based on HPC workload profile
 - HyperThreading
 - SubNumaCluster
 - ADDDC
- GPUs
 - V100-PCIe/SXM2
 - V100S
 - RTX 6000/8000
- Server
 - C4140
 - DSS8440
 - R740

Tuning Knobs - SW

- Docker version
- Binding with CPU cores
- OS
 - Spectre/Meltdown patches
 - Dist/Release/Kernel
- GPU Driver
- CUDA toolkit version
- NCCL
 - Tree vs Ring
 - P2P
- CuDNN
- DALI

- Hyperparameters
 - Batch size
 - Learning rate
 - Etc.
- Frameworks
 - Tensorflow
 - Pytorch
 - MXNet
 - Horovod

MLPerf training v6.0 tuning result



MLPerf v0.6 Converged time on DSS8440

Haven't try everything on every subtests, some of them applied, and it is good enough for showing the difference before and after tuning

•

Know when to stop

- Tuning is time consuming
- Set expectation
- Compare with known results from MLPerf website
 - Hyperparameters
 - Converged with less or equal epoch_num
 - Average results
 - Refer to tokens/s, images/s
- Watch GPU utilization >90 TDP > 200/250 W
- Profiling
- Run with multiple systems will help to speed up

Suggestions for single node tuning

- Run on latest OS or newer kernel
- Use NCCL matching your hardware layout
- Use new CUDA libraries
 - Improved performance
 - Additional parameters
- Explorer settings in Dockerfile, run.sub, run_and_time, config_DGX1.sh, compare with DGX2's
- Use submitted results files as reference

Build docker with latest libraries

- [root@node009 gnmt]# cat Dockerfile
- ARG FROM_IMAGE_NAME=nvcr.io/nvidia/pytorch:19.05-py3
- FROM \${FROM_IMAGE_NAME}
- # Install dependencies for system configuration logger
- RUN wget https://developer.download.nvidia.com/compute/machine-learning/repos/ubuntu1604/x86_64/nvidia-machine-learning-repo-ubuntu1604_1.0.0-1_amd64.deb
 & dpkg -i nvidia-machine-learning-repo-ubuntu1604_1.0.0-1_amd64.deb
- RUN apt-get update && apt-get install -y --no-install-recommends \
- infiniband-diags \
- pciutils \
- libnccl2 libnccl-dev libcudnn7 libcudnn7-dev && \
- rm -rf /var/lib/apt/lists/* #&& rm nvidia-machine-learning-repo-ubuntu1604_1.0.0-1_amd64.deb
- # Rebuild PyTorch
- WORKDIR /opt/pytorch
- RUN cd pytorch && \
- TORCH_CUDA_ARCH_LIST="5.2 6.0 6.1 7.0 7.5+PTX" \
- CMAKE_PREFIX_PATH="\$(dirname \$(which conda))/../"
- NCCL_INCLUDE_DIR="/usr/include/" \
- NCCL_LIB_DIR="/usr/lib/" \
- python setup.py install && python setup.py clean
- # Install Python dependencies
- WORKDIR /workspace/rnn_translator
- COPY requirements.txt .
- * RUN pip install --no-cache-dir https://github.com/mlperf/training/archive/6289993e1e9f0f5c4534336df83ff199bd0cdb75.zip#subdirectory=compliance \
- && pip install --no-cache-dir -r requirements.txt
- # Copy & build extensions
- COPY seq2seq/csrc seq2seq/csrc
- COPY setup.py .
- RUN pip install .
- # Copy GNMT code
- COPY . .
- # Configure environment variables
- ENV LANG C.UTF-8



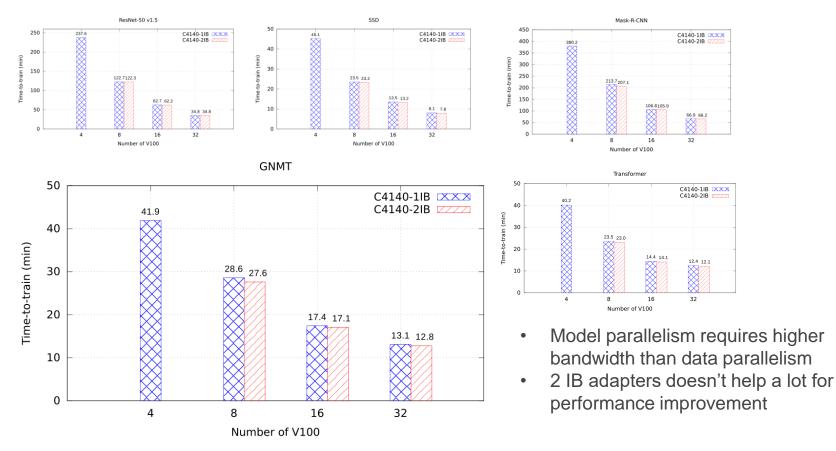
Multiple nodes



MLPerf multiple nodes training

- Not easy to use Docker on multi-node with InfiniBand
 - The InfiniBand driver version within Docker container may not match the version on the host
 - The docker container may not update the IB driver automatically
- Solution:
 - convert the base Docker container into Singularity container
 - build MLPerf benchmarks within Singularity container
 - run Singularity container with Slurm

MLPerf Training on C4140

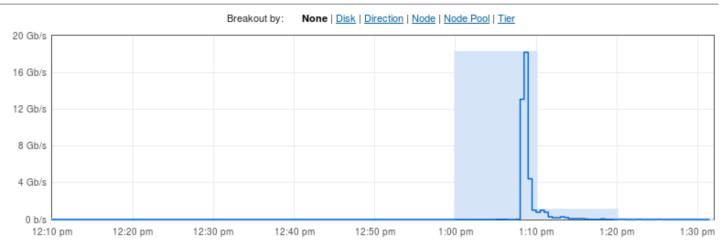


Storage Profiling

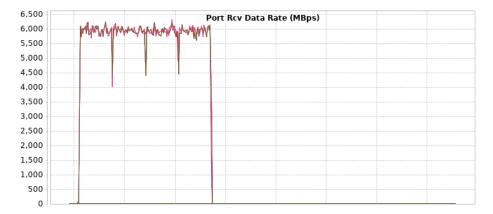


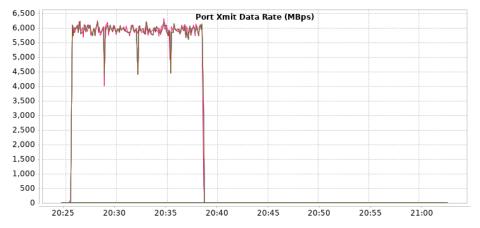
Disk Throughput Rate 🔞

Download as CSV



Network Profiling







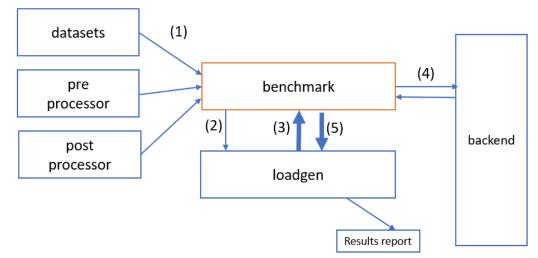
Storage and Network Profiling

		ResNet-50	SSD	Mask-R-CNN	GNMT	Transformer
Storage	2 nodes	7.4	3.9	0.2	0.19	0.26
(Gb/s)	4 nodes	16	3.1	0.42	0.28	0.34
	8 nodes	18	4.8	1.2	0.3	0.26
Network (Gb/s)	2 nodes	3.8	1.4	4.4	12	11.6
	4 nodes	4	4.8	7.6	36	24.8
	8 nodes	4.2	7.6	7.2	48	24.8

Inference v0.5

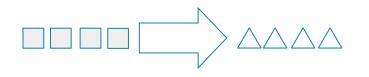


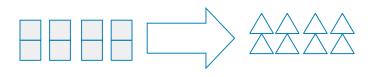
MLPerf Inference v0.5 Benchmark



- 1 benchmark knows dataset
- 2 benchmark hands content id's to loadgen
- 3 loadgen starts generating queries
- 4 benchmark creates requests to backend
- 5 benchmark post processes response and completes query
- 6 after all queries finished, loadgen writes report

Area	Task	Model	Dataset
Vision	Image classification	ResNet50-v1.5	lmageNet (224x224)
Vision	lmage classification	MobileNets-v1 224	lmageNet (224x224)
Vision	Object detection	SSD-ResNet34	COCO (1200x1200)
Vision	Object detection	SSD-MobileNets-v1	COCO (300x300)
Language	Machine translation	GNMT	WMT16



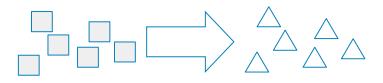


Single stream e.g. cell phone augmented vision

Multiple stream e.g. multiple camera driving assistance

Latency

Number streams subject to latency bound



Server e.g. translation site

QPS

subject to latency bound

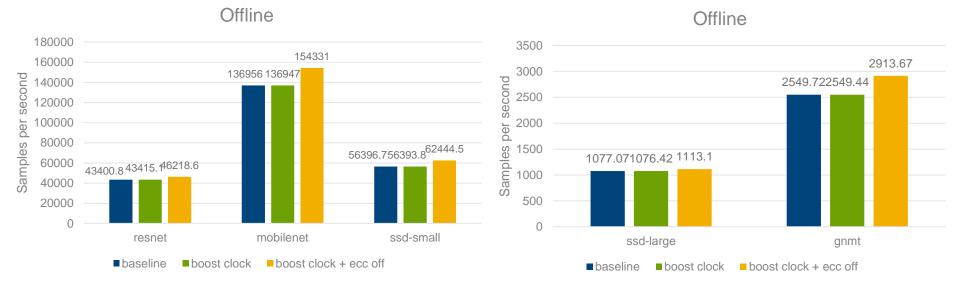
Offline

e.g. photo sorting

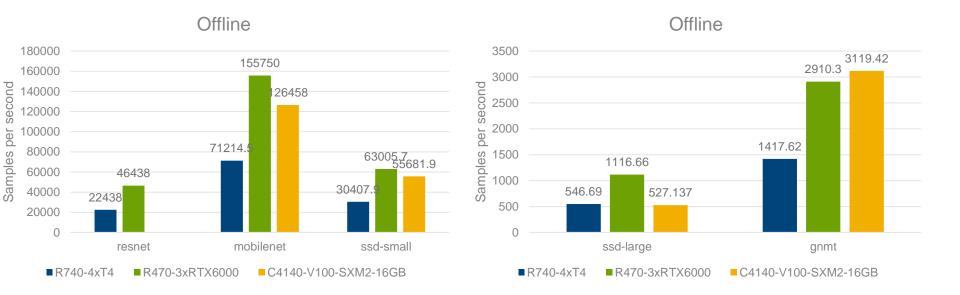
Throughput

Source: https://arxiv.org/pdf/1911.02549.pdf

- Test Server: R740/C4140
- GPUs: 4x T4/ 3x RTX6000 /4x V100-SXM2 16GB
- Inference Backend: TensorRT 6.0
- Benchmarks:
 - ResNet50-v1.5
 - MobileNet
 - SSD-MobileNets-v1
 - SSD-ResNet34
 - GNMT
- Inference Scenarios: Server, Offline



- Tested with 3x RTX 6000
 - Boost clock does not improve the performance
 - ECC off can improve the performance by 3.41% to 14.29%



- RTX is 2.7x 2.9x faster than T4 per GPU
- RTX is 2.8x faster than V100 per GPU for ssd-large, and 1.2x 1.6x for other models

- The goal for Server scenario: find the maximum QPS subject to latency bound.
- Search strategy: binary search. The initial left boundary is valid QPS, the initial right boundary is invalid QPS.
- while(left < right){

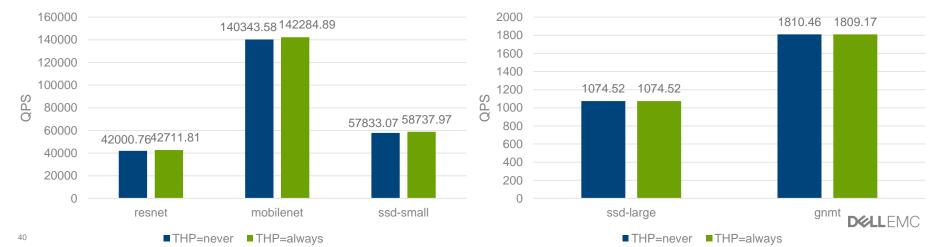
right – 1 is the maximum QPS when the result is VALID

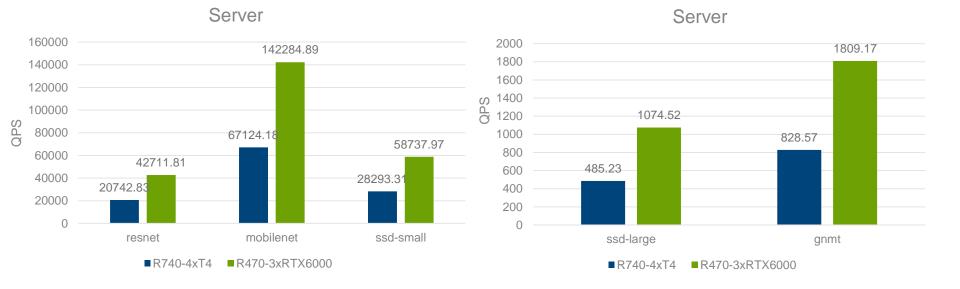
• }

- Use jemalloc: scalable concurrency support and reducing memory fragmentation
 - LD_PRELOAD=/usr/lib/x86_64-linux-gnu/libjemalloc.so.2
- Use Transparent Huge Pages (THP)
 - Performance improvement of 1.69%, 1.38%, and 1.56% for resnet, mobilenet, and ssd-small
 - No improvement for ssd-large and gnmt









• RTX is 2.7x – 2.9x faster than T4 per GPU

Conclusions

Training

- Docker is not easy to use on multi-node with InfiniBand, an alternate is to use Singularity container
- The performance scales well for ResNet-50 v1.5, SSD and Mask-R-CNN.
- The machine translation models (GNMT and Transformer) have (or need) high network throughput.
- Dual IB does not have significant performance improvement.

Inference

- Boost clock does not improve the performance
- ECC off can improve the performance obviously
- jemalloc library makes the Server scenario performance more stable
- Transparent Huge Pages (THP) provide performance benefits for Server scenario
- Binary search can search the right QPS for Server scenario efficiently

DELEMC